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 Adaptive Control Design and Analysis
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JILLIAN SANCHEZ

Feedback Systems Springer

Adaptive filtering is a topic of immense practical and theoretical value, having applications in areas ranging from digital and wireless communications to biomedical systems. This book enables readers to gain a gradual and solid introduction to the subject, its applications to a variety of topical problems, existing limitations, and extensions of current theories. The book consists of eleven parts, each part containing a series of focused lectures and ending with bibliographic comments, problems, and computer projects with MATLAB solutions.

Flight Dynamics and Control of Aero and Space Vehicles Springer Science & Business Media

Designed to meet the needs of a wide audience without sacrificing mathematical depth and rigor, Adaptive Control Tutorial presents the design, analysis, and application of a wide variety of algorithms that can be used to manage dynamical systems with unknown parameters. Its tutorial-style presentation of the fundamental techniques and algorithms in adaptive control make it suitable as a textbook. Adaptive Control Tutorial is designed to serve the needs of three distinct groups of readers: engineers and students interested in learning how to design, simulate, and implement parameter estimators and adaptive control schemes without having to fully understand the analytical and technical proofs; graduate students who, in addition to attaining the aforementioned objectives, also want to understand the analysis of simple schemes and get an idea of the steps involved in more complex proofs; and advanced students and researchers who want to study and understand the details of long and technical proofs with an eye toward pursuing research in adaptive control or related topics. The authors achieve these multiple objectives by enriching the book with examples demonstrating the design procedures and basic analysis steps and by detailing their proofs in both an appendix and electronically available supplementary material; online examples are also available. A solution manual for instructors can be obtained by contacting SIAM or the authors. Preface; Acknowledgements; List of Acronyms; Chapter 1: Introduction; Chapter 2: Parametric Models; Chapter 3: Parameter Identification: Continuous Time; Chapter 4: Parameter Identification: Discrete Time; Chapter 5: Continuous-Time Model Reference Adaptive Control; Chapter 6: Continuous-Time Adaptive Pole Placement Control; Chapter 7: Adaptive Control for Discrete-Time Systems; Chapter 8: Adaptive Control of Nonlinear Systems; Appendix; Bibliography; Index

Robotics Princeton University Press

During the past decade there has been an explosion in computation and information technology. With it have come vast amounts of data in a variety of fields such as medicine, biology, finance, and marketing. The challenge of understanding these data has led to the development of new tools in the field of statistics, and spawned new areas such as data mining, machine learning, and bioinformatics. Many of these tools have common underpinnings but are often expressed with different terminology. This book describes the important ideas in these areas in a common conceptual framework. While the approach is statistical, the emphasis is on concepts rather than mathematics. Many examples are given, with a liberal use of color graphics. It should be a valuable resource for statisticians and anyone interested in data mining in science or industry. The book's coverage is broad, from supervised learning (prediction) to unsupervised learning. The many topics include neural networks, support vector machines, classification trees and boosting--the first comprehensive treatment of this topic in any book. This major new edition features many topics not covered in the original, including graphical models, random forests, ensemble methods, least angle regression & path algorithms for the lasso, non-negative matrix factorization, and spectral clustering. There is also a chapter on methods for "wide" data (p bigger than n), including multiple testing and false discovery rates. Trevor Hastie, Robert Tibshirani, and Jerome Friedman are

professors of statistics at Stanford University. They are prominent researchers in this area: Hastie and Tibshirani developed generalized additive models and wrote a popular book of that title. Hastie co-developed much of the statistical modeling software and environment in R/S-PLUS and invented principal curves and surfaces. Tibshirani proposed the lasso and is co-author of the very successful An Introduction to the Bootstrap. Friedman is the co-inventor of many data-mining tools including CART, MARS, projection pursuit and gradient boosting.

Stability, Convergence and Robustness Springer Science & Business Media

Exploring connections between adaptive control theory and practice, this book treats the techniques of linear quadratic optimal control and estimation (Kalman filtering), recursive identification, linear systems theory and robust arguments.

Next Generation Solutions Springer Science & Business Media

This open access Brief introduces the basic principles of control theory in a concise self-study guide. It complements the classic texts by emphasizing the simple conceptual unity of the subject. A novice can quickly see how and why the different parts fit together. The concepts build slowly and naturally one after another, until the reader soon has a view of the whole. Each concept is illustrated by detailed examples and graphics. The full software code for each example is available, providing the basis for experimenting with various assumptions, learning how to write programs for control analysis, and setting the stage for future research projects. The topics focus on robustness, design trade-offs, and optimality. Most of the book develops classical linear theory. The last part of the book considers robustness with respect to nonlinearity and explicitly nonlinear extensions, as well as advanced topics such as adaptive control and model predictive control. New students, as well as scientists from other backgrounds who want a concise and easy-to-grasp coverage of control theory, will benefit from the emphasis on concepts and broad understanding of the various approaches.

Adaptive Control Design and Analysis SIAM

Although LMI has emerged as a powerful tool with applications across the major domains of systems and control, there has been a need for a textbook that provides an accessible introduction to LMIs in control systems analysis and design. Filling this need, LMIs in Control Systems: Analysis, Design and Applications focuses on the basic analysis and

Methods and Applications Springer

Suitable for advanced undergraduates and graduate students, this overview introduces theoretical and practical aspects of adaptive control, with emphasis on deterministic and stochastic viewpoints. 1995 edition.

Adaptive Control of Chemical Processes 1985 CRC Press

Adaptive Control provides techniques for automatic, real-time adjustments in controller parameters with a view to achieving and/or maintaining a desirable level of system performance in the presence of unknown or variable process parameters. Many aspects of the field are dealt with in coherent and orderly fashion, starting with the problems posed by system uncertainties and moving on to the presentation of solutions and their practical significance. Within the general context of recent developments, the book looks at: • synthesis and analysis of parameter adaptation algorithms; • recursive plant-model identification in open and closed loop; • robust digital control for adaptive control; • direct and indirect adaptive control; and • practical aspects and applications. To reflect the importance of digital computers for the application of adaptive control techniques, discrete-time aspects are emphasized. To guide the reader, the book contains various applications of adaptive control techniques.

Applied Nonlinear Control Springer Science & Business Media

Robust Adaptive Control Courier Corporation

Optimal State Estimation Robust Adaptive Control

Flight Vehicle Dynamics and Control Rama K. Yedavalli, The Ohio State University, USA A comprehensive textbook which presents flight vehicle dynamics and control in a unified framework

Flight Vehicle Dynamics and Control presents the dynamics and control of various flight vehicles, including aircraft, spacecraft, helicopter, missiles, etc, in a unified framework. It covers the fundamental topics in the dynamics and control of these flight vehicles, highlighting shared points as well as differences in dynamics and control issues, making use of the 'systems level' viewpoint. The book begins with the derivation of the equations of motion for a general rigid body and then delineates the differences between the dynamics of various flight vehicles in a fundamental way. It then focuses on the dynamic equations with application to these various flight vehicles, concentrating more on aircraft and spacecraft cases. Then the control systems analysis and design is carried out both from transfer function, classical control, as well as modern, state space control points of view. Illustrative examples of application to atmospheric and space vehicles are presented, emphasizing the 'systems level' viewpoint of control design. Key features: Provides a comprehensive treatment of dynamics and control of various flight vehicles in a single volume. Contains worked out examples (including MATLAB examples) and end of chapter homework problems. Suitable as a single textbook for a sequence of undergraduate courses on flight vehicle dynamics and control. Accompanied by a website that includes additional problems and a solutions manual. The book is essential reading for undergraduate students in mechanical and aerospace engineering, engineers working on flight vehicle control, and researchers from other engineering backgrounds working on related topics.

Modelling and Control of Robot Manipulators John Wiley & Sons

Includes a solution manual for problems. Provides MATLAB code for examples and solutions. Deals with robust systems in both theory and practice.

Proceedings of the IFAC Workshop, Frankfurt/Main, 21-22 October 1985 Courier Corporation

Leading experts present the latest research results in adaptive signal processing Recent developments in signal processing have made it clear that significant performance gains can be achieved beyond those achievable using standard adaptive filtering approaches. Adaptive Signal Processing presents the next generation of algorithms that will produce these desired results, with an emphasis on important applications and theoretical advancements. This highly unique resource brings together leading authorities in the field writing on the key topics of significance, each at the cutting edge of its own area of specialty. It begins by addressing the problem of optimization in the complex domain, fully developing a framework that enables taking full advantage of the power of complex-valued processing. Then, the challenges of multichannel processing of complex-valued signals are explored. This comprehensive volume goes on to cover Turbo processing, tracking in the subspace domain, nonlinear sequential state estimation, and speech-bandwidth extension. Examines the seven most important topics in adaptive filtering that will define the next-generation adaptive filtering solutions Introduces the powerful adaptive signal processing methods developed within the last ten years to account for the characteristics of real-life data: non-Gaussianity, non-circularity, non-stationarity, and non-linearity Features self-contained chapters, numerous examples to clarify concepts, and end-of-chapter problems to reinforce understanding of the material Contains contributions from acknowledged leaders in the field Adaptive Signal Processing is an invaluable tool for graduate students, researchers, and practitioners working in the areas of signal processing, communications, controls, radar, sonar, and biomedical engineering.

Second Edition CRC Press

Comprehensive and up to date coverage of robust control theory and its application • Presented in a well-planned and logical way • Written by a respected leading author, with extensive experience in robust control • Accompanying website provides solutions manual and other supplementary material

Robust Adaptive Control Wiley-Interscience

Methods by which robots can learn control laws that enable real-time reactivity using dynamical systems; with applications and exercises. This book presents a wealth of machine learning techniques to make the control of robots more flexible and safe when interacting with humans. It introduces a set of control laws that enable reactivity using dynamical systems, a widely used method for solving motion-planning problems in robotics. These control approaches can replan in milliseconds to adapt to new environmental constraints and offer safe and compliant control of forces in contact. The techniques offer theoretical advantages, including convergence to a goal, non-penetration of obstacles, and passivity. The coverage of learning begins with low-level control parameters and progresses to higher-level competencies composed of combinations of skills. Learning for Adaptive and Reactive Robot Control is designed for graduate-level courses in robotics, with chapters that proceed from fundamentals to more advanced content. Techniques covered include learning from demonstration, optimization, and reinforcement learning, and using dynamical systems in learning control laws, trajectory planning, and methods for compliant and force control . Features for teaching in each chapter: • applications, which range from arm manipulators to whole-body control of humanoid robots; • pencil-and-paper and programming exercises; • lecture videos, slides, and MATLAB code examples available on the author's website . • an eTextbook platform website offering protected material[EPS2] for instructors including solutions.

A Dynamical Systems Approach Springer Science & Business Media

The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions,

reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory

Adaptive Signal Processing John Wiley & Sons

In this work, the authors present a global perspective on the methods available for analysis and design of non-linear control systems and detail specific applications. They provide a tutorial exposition of the major non-linear systems analysis techniques followed by a discussion of available non-linear design methods.

Robust and Adaptive Control Princeton University Press

The standard theory of decision making under uncertainty advises the decision maker to form a statistical model linking outcomes to decisions and then to choose the optimal distribution of outcomes. This assumes that the decision maker trusts the model completely. But what should a decision maker do if the model cannot be trusted? Lars Hansen and Thomas Sargent, two leading macroeconomists, push the field forward as they set about answering this question. They adapt robust control techniques and apply them to economics. By using this theory to let decision makers acknowledge misspecification in economic modeling, the authors develop applications to a variety of problems in dynamic macroeconomics. Technical, rigorous, and self-contained, this book will be useful for macroeconomists who seek to improve the robustness of decision-making processes.

A Primer John Wiley & Sons

Modern medical imaging and radiation therapy technologies are so complex and computer driven that it is difficult for physicians and technologists to know exactly what is happening at the point-of-care. Medical physicists responsible for filling this gap in knowledge must stay abreast of the latest advances at the intersection of medical imaging and radiation therapy. This book provides medical physicists and radiation oncologists current and relevant information on Adaptive Radiation Therapy (ART), a state-of-the-art approach that uses a feedback process to account for patient-specific anatomic and/or biological changes, thus delivering highly individualized radiation therapy for cancer patients. The book should also benefit medical dosimetrists and radiation therapists. Adaptive Radiation Therapy describes technological and methodological advances in the field of ART, as well as initial clinical experiences using ART for selected anatomic sites. Divided into three sections (radiobiological basis, current technologies, and clinical applications), the book covers: Morphological and biological biomarkers for patient-specific planning Design and optimization of treatment plans Delivery of IMRT and IGRT intervention methodologies of ART Management of intrafraction variations, particularly with respiratory motion Quality assurance needed to ensure the safe delivery of ART ART applications in several common cancer types / anatomic sites The technology and methodology for ART have advanced significantly in the last few years and accumulated clinical data have demonstrated the need for ART in clinical settings, assisted by the wide application of intensity modulated radiation therapy (IMRT) and image-guided radiation therapy (IGRT). This book shows the real potential for supplying every patient with individualized radiation therapy that is maximally accurate and precise.

Adaptive Filters Springer Science & Business Media

This textbook provides readers with a good working knowledge of adaptive control theory through applications. It is intended for students beginning masters or doctoral courses, and control practitioners wishing to get up to speed in the subject expeditiously. Readers are taught a wide variety of adaptive control techniques starting with simple methods and extending step-by-step to more complex ones. Stability proofs are provided for all adaptive control techniques without obfuscating reader understanding with excessive mathematics. The book begins with standard model-reference adaptive control (MRAC) for first-order, second-order, and multi-input, multi-output systems. Treatment of least-squares parameter estimation and its extension to MRAC follow, helping readers to gain a different perspective on MRAC. Function approximation with orthogonal polynomials and neural networks, and MRAC using neural networks are also covered. Robustness issues connected with MRAC are discussed, helping the student to appreciate potential pitfalls of the technique. This appreciation is encouraged by drawing parallels between various aspects of robustness and linear time-invariant systems wherever relevant. Following on from the robustness problems is material covering robust adaptive control including standard methods and detailed exposition of recent advances, in particular, the author's work on optimal control modification. Interesting properties of the new method are illustrated in the design of adaptive systems to meet stability margins. This method has been successfully flight-tested on research aircraft, one of various flight-control applications detailed towards the end of the book along with a hybrid adaptive flight control architecture that combines direct MRAC with least-squares indirect adaptive control. In addition to the applications, understanding is encouraged by the use of end-of-chapter exercises and associated MATLAB® files. Readers will need no more than the standard mathematics for basic control theory such as differential equations and matrix algebra; the book covers the foundations of MRAC and the necessary mathematical preliminaries.

Adaptive Control John Wiley & Sons

Includes a solution manual for problems. Provides MATLAB code for examples and solutions. Deals with robust systems in both theory and practice.